Paris-ACP, 17-Jan-2008, "Nancay LOFAR-SS"

LOFAR specs (rescoped), some CS-1 results and (long) baseline calibration issues

Ger de Bruyn

(LOFAR Calibration Project Scientist)

Outline:

- 1. LOFAR configuration overview and rescope effect
- 2. uv-coverage in core, LOFAR core 'superstation'
- 3. FOV, *#* sources and sensitivity
- 4. CS-1 and WSRT-LFFE: some lessons learned
- 5. Review of main calibration issues
- 6. Some long baseline (~500-1000 km) calibration issues

The LOFAR observatory

Frequency ranges : LBA 20 - 80 MHz HBA 115 - 240 MHz Collecting area: ~ 0.03 - 0.06 km² Dimension at start ~ 100 km eventually > 1000 km (Eu-LOFAR)

Configuration: 40 - 50 stations (of 24 - 96 antennas)core (~ 2 km diameter)20 - 50 stations+ '5-armed spiral / expo shell'20 - 25 stations

Phased array of dipoles Aperture synthesis array like: WSRT, VLA, GMRT..

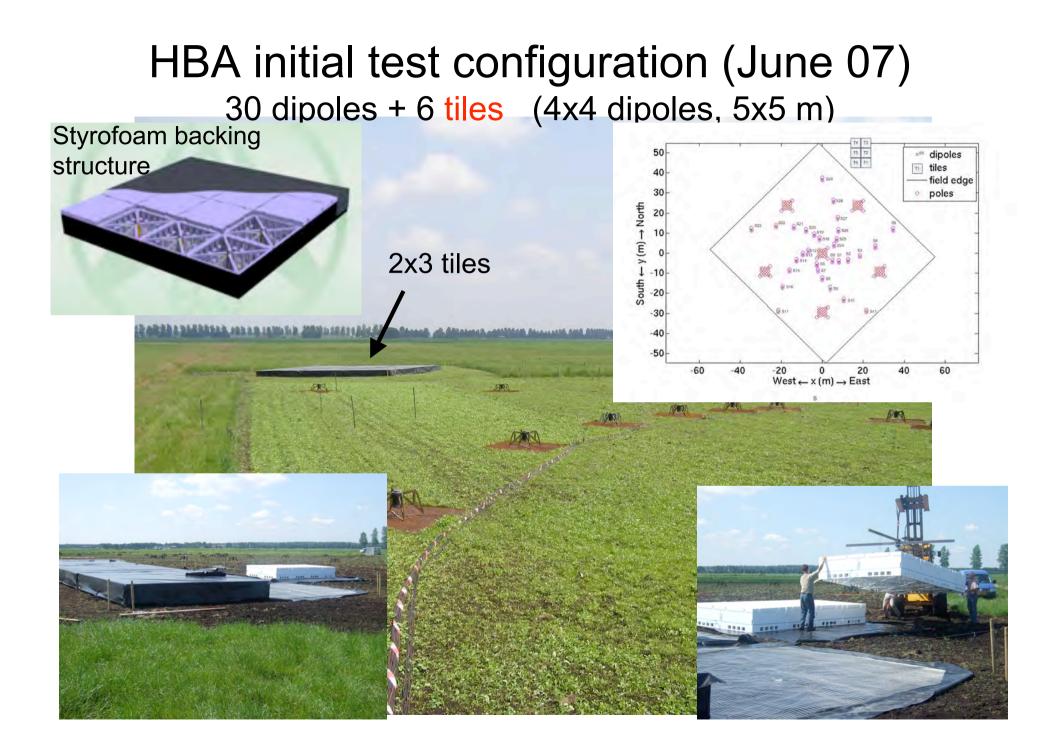
Sensitivity (after 4 h, 4 MHz) - @ 50 MHz ~ 5 mJy - @ 150 MHz ~ 0.3 mJy

Many simultaneous users (beams) possible !

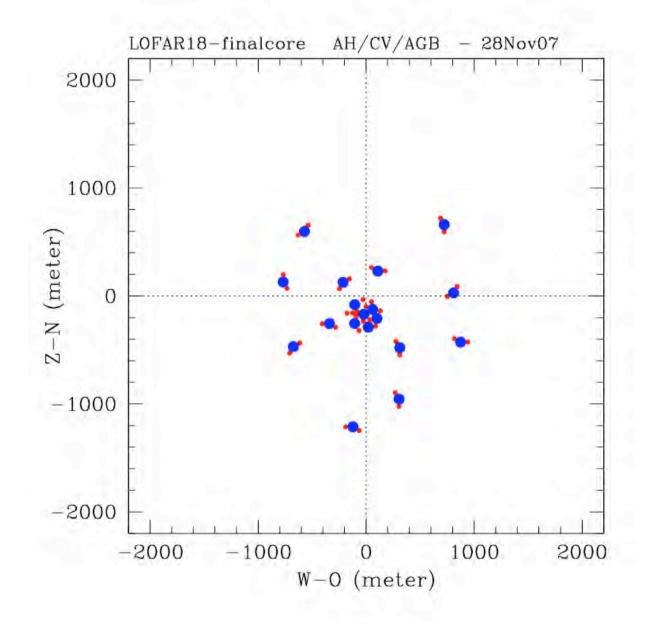
descoped / preliminary

hybrid array ! (Sep07)

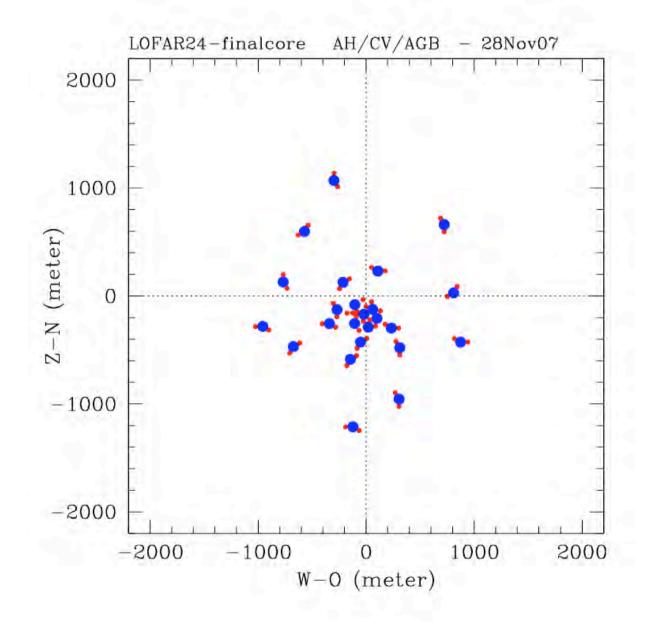




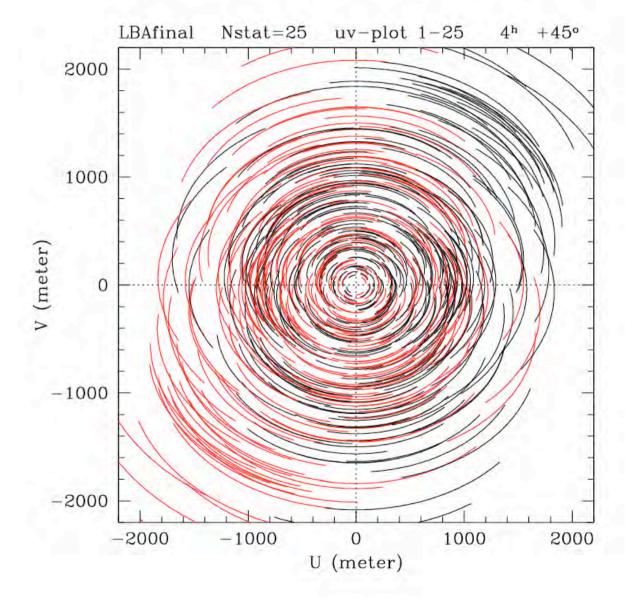
LOFAR18 core



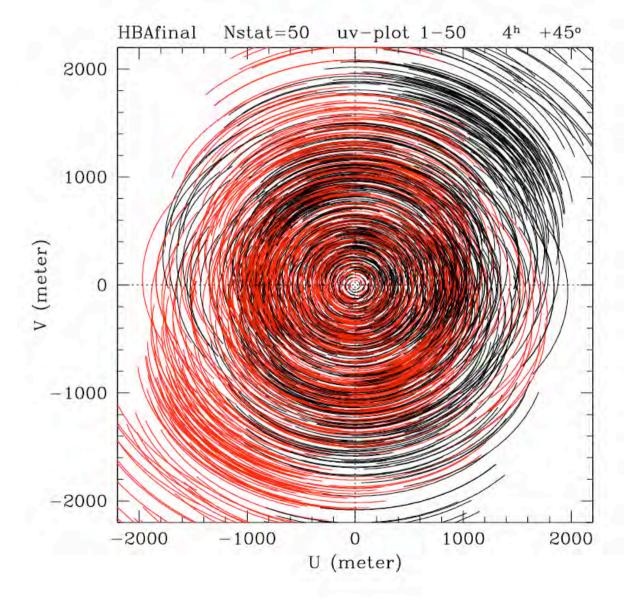
LOFAR24 core



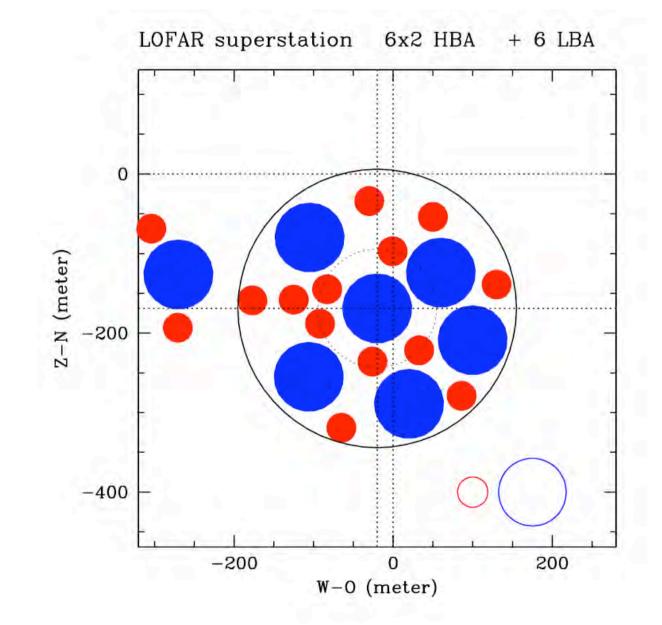
LBA 25 stations 4^{h} +45°



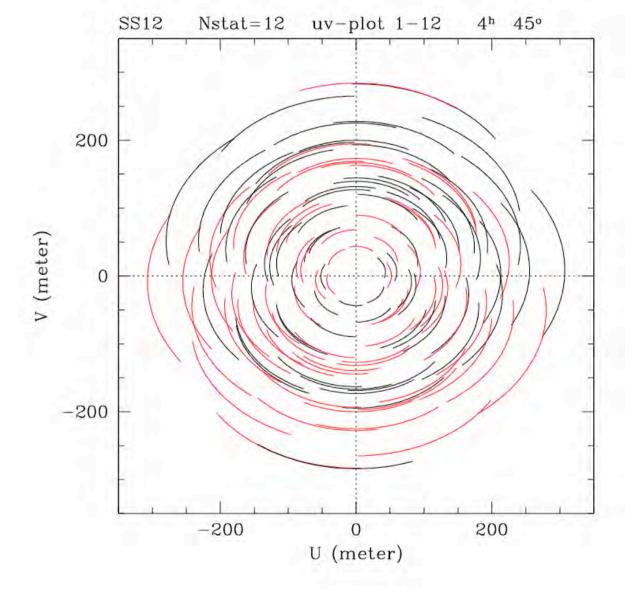
HBA 25x2 stations 4^{h} +45°



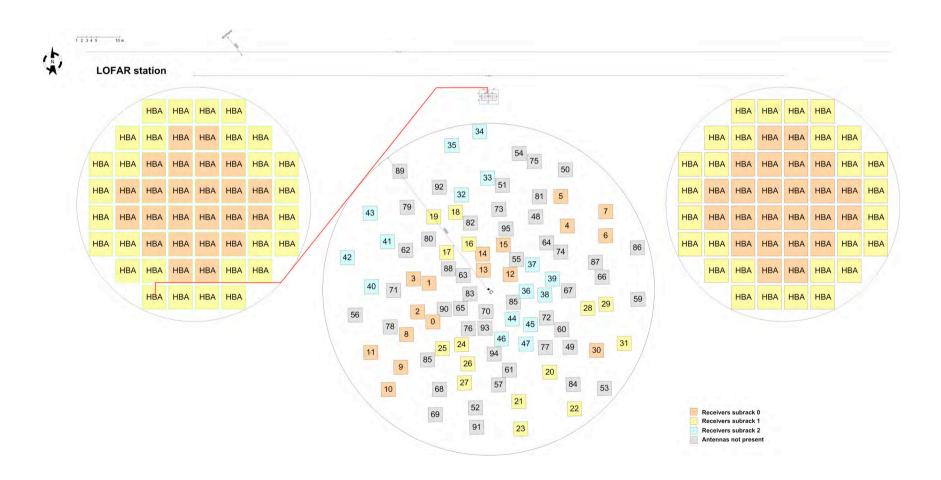
'Superstation' in core: 6 LBA and 6x2 HBA



6x2 HBA uv-coverage 4^h +45^o



Core station layout after rescope HBA24 LBA48-96 HBA24



LOFAR sensitivity table (Dec07)

HBA (150 M	Hz)	Unit	LBA	(50 MHz)
YY	Sta	tion no	oise	
1 dipole	1,600,000	Jy	1,600,000	1 dipole
1 4x4 tile	100,000	Jy		I Lado and a second
1 24-tile station (core)	4,200	Jy		
	0 100	In	33,000	1 48-dipole station
1 48-tile station (NL)	2,100	Jy	55,000	1 40-uipoic station
1 96 tile station (EU)	1,050 Visibility	Jy noise	20,000 (core arra	1 96-dipole station
1 96 tile station (EU)	1,050 Visibility 3.1	Jy noise	20,000 (core arra 25	1 96-dipole station
1 96 tile station (EU)	1,050 Visibility	Jy noise	20,000 (core arra	1 96-dipole station
1 96 tile station (EU) 1 ifr, 10s, 1pol, 0.18 MHz 1 ifr, 10s, 1pol, 20x0.18 MHz	1,050 Visibility 3.1 0.7 apshot ima 78	Jy noise Jy Jy Jy	20,000 (core arra 25	1 96-dipole station (y) 5

N=40

N=60

N=40

N=20

1770 ifrs, 4h, 2 pol, 0.18 MHz	1.0	mJy	22	780 ifrs
1770 ifrs, 4h, 2 pol, 20x0.18MHz	0.22	mJy	4.8	780 ifrs
1770 ifrs, 4h, 2 pol, 164x0.18MHz	0.08	mJy	1.7	780 ifrs

LOFAR beam/FOV table

LOFAR station diameter and resulting FOV in HBA and LBA bands (after Oct2007 rescope)

HBA			120 MHz	220 MHz
Array	# tiles/station	station diameter (m)	HPBW (deg)	HPBW(deg)
Core	24 +24	~ 35	~ 5.3	~ 2.9
NL	48	~ 50	~ 3.7	~ 2.0
Europe	96	~ 65	~ 2.9	~1.6

Adopted HBPW = $1.3 \lambda / D$ (depends on beamformer spatial taper used) Note that the synthesized FOV has to be typically ~ 2x larger !

On core-NL, core-EU or NL-EU baselines the geometric mean values have to be taken !

LBA			30 MHz	60 MHz	
Array	# dipoles/station	station diameter(m)	HPBW (deg)	HPBW(deg)	
Core	48	~ 30 - 82m	9.1 (for 82m)	12.4 (for 30m)	
NL	48	~ 30 - 82m	9.1 (for 82m)	12.4 (for 30m)	
Europe	96	65	11.5	5.7	

Example !

3.8°

Excel sheets to give sensitivity, FOV, # sources (S/N) etc for rescoped core, NL and European LOFAR arrays (Nijboer & de Bruyn, in prep)

Note: Vellow fields are inputs

÷	LBA Core Stations-
÷	LBA Remote Stations
4	LBA EU Stations
1	HBA Core Sations
1	HBA Remote Stations
	HBA EU Stations

HBA dipole noise (Jv) 150 MHz

Effective width of a subband (Hz)

Image noise increase factor: Core Image noise increase factor: Core + Remote Image noise increase factor: Core + Remote + EU

1900000.00

1.30

Incise per tile 1600000.00 1600000.00 1600000.00 100000.00	16 95						
Core Remote EU Core Remote EU Core 33333.33 33333.33 25670.23 4165.67 2946.28	0000.00 0000.00 1041.67						
Core 33333.33 33333.33 25670.23 4166.67 2946.28							
EU 16666.67	2083.33 1673.14 1041.67						
Note per baserine, 10 s., 1 subbartid, 1 por Core Remote EU Core Remote EU							
Core Remote EU Core Remote EU Core 24.85 24.85 17.57 3.11 2.20 Remote 24.85 24.85 47.57 3.11 2.20 EU 24.85 47.57 1.55 1.55	1.55 1.10 0.78						
None per pasenere, 10 s., 20 subcare, 1 pol							
Core Remote EU Core Remote EU Core 5.56 5.56 3.63 0.69 0.49 Remote 5.56 3.63 0.69 0.35 EU 2.78 2.78 0.55	0.35 0.25 0.17						
# baselines							
Core Remote EU Core Remote EU Core 190 400 0 780 800 Remote 190 0 190 190 190 EU 0 0 190 190 190	000						
Image noise 1 s _ 1 Hz, 1 pol. (Jy) Note: assuming equal weighting of all baselines, but including the increase in noise factor							
Core Core + Remote Core + Remote Core + Remote 2418 25 1551.58 1551.58 149.19 95.58	* EU 36.66						
Snapshot image noise (mJy) 10 sec. 1 subband, 2 pol 1274.53 817.76 817.76 78.63 50.96 10 sec. 1 subband, 2 pol 1284.99 182.86 182.86 17.58 11.39 10 sec., 184 subband, 2 pol 19.52 63.88 63.88 6.14 3.96	\$0.95 11.39 3.98						
Synthesis image noise (mJy).							
4 hr. 1 subband. 2 pol 33.59 21.55 21.55 20.7 1.34 4 hr. 20 subband. 2 pol 7.51 4.82 4.62 0.45 0.30 4 hr., 164 subband, 2 pol 2.82 1.68 1.68 0.18 0.10	1.34 0.30 0.10						

Note: increase in image noise due to weighting scheme

Note: average elevation of 45 degrees (projection factor 0.7)

Note: flanks of the subbands will be neglected and some channels will be flagged for RFI

Some results from LOFAR CS-1 (Core Station 1)

CS-1 frequency selection aspects

Sampling modes: 160 or 200 MHz --> LBA & HBA frequency modes

- Station: 512 subbands (156 or 195 kHz)
- CEP: per subband 256 channels (0.6 or 0.8 kHz)

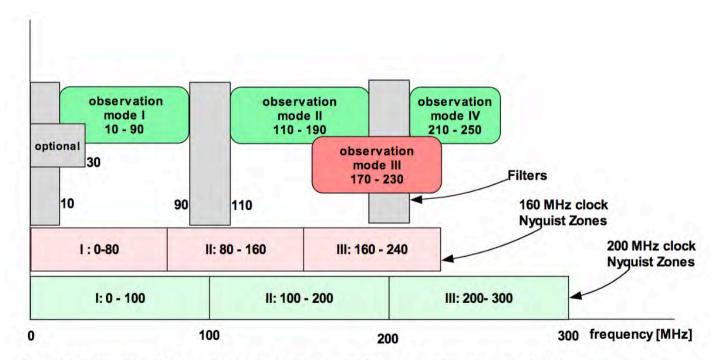
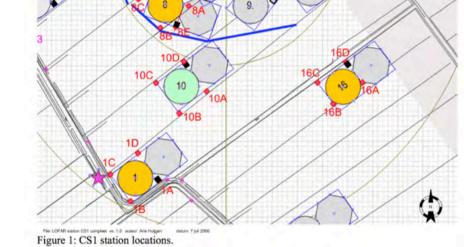


Figure 10 Selection of Nyquist zones is used to select the observed band in the station.

CS-1 configuration ('mini'-LOFAR) Dec 06 --> Summer 08

- hardware across 4 stations:
 - LBA: 96 dipoles (48 + 3x16)
 - HBA: 32 dipoles + 6 tiles
- per station there are 4 -12 'micro'stations
- digital beamforming (with 4 48 dipoles)
- baselines from ~10 450 meter
- 16 'micro' stations \Rightarrow 120 (\sim 60) interferometers
- 24 microstations \Rightarrow 276 (~ 180) interferometers

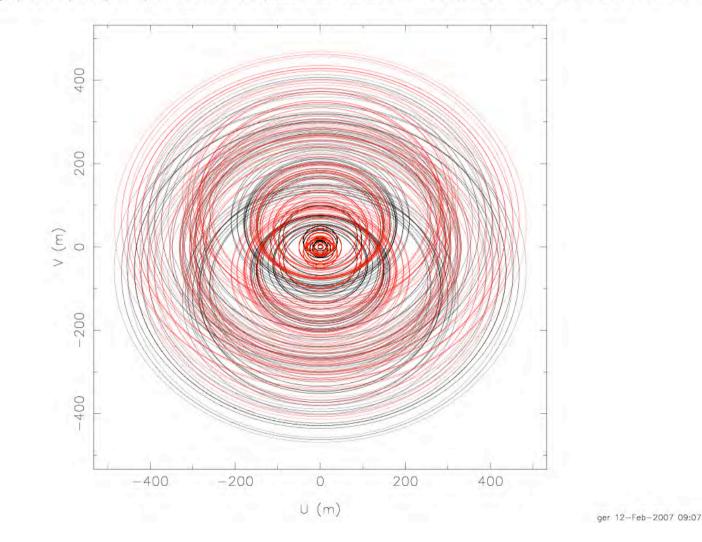


CS1 compleet: Op veld 10 (groen) wordt de bekabeling ingegraven. Veld 8, 1 en 16 worden slechts gevlakt

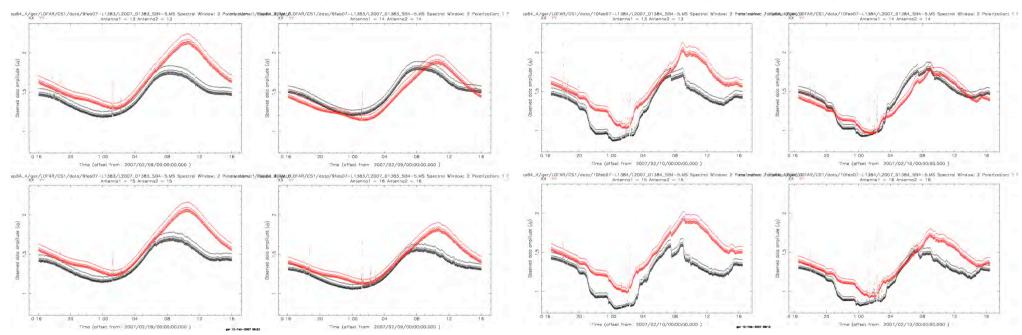


CS-1 uv-coverage (projected baseline+orientation) after 24 h on CasA, dec +59°

p64_4/ger/LOFAR/CS1/data/10feb07-L1384/L2007_01384_SB4-5.MS Spectral Window: 2 Polarization: 1 F



(indirect) effects of rain on total power (gain) dry day very wet day



- Rain: resonance frequency of antenna shifts down in frequency -->
- Gain effects typically ~ +10% (v < 58 MHz) or ~ -10 % (v > 58 MHz)

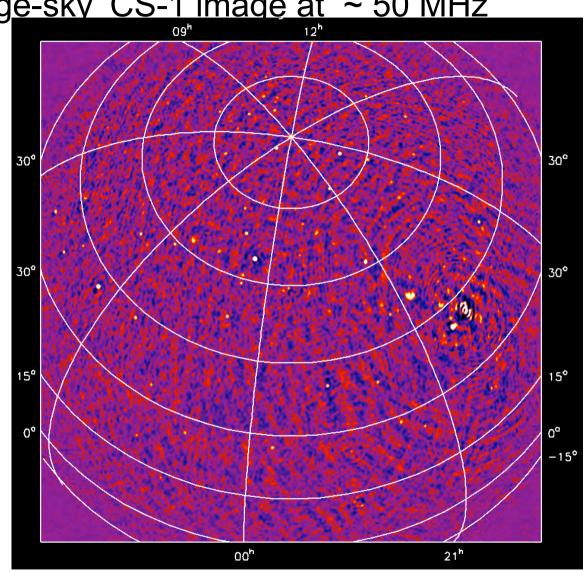
How will we deal with this?

1) correct through selfcalibration or 2) observe with HBA's and 3) reduce effects (?)

First high quality 'larg<u>e-sky' CS-1 image at ~ 50 MHz</u>

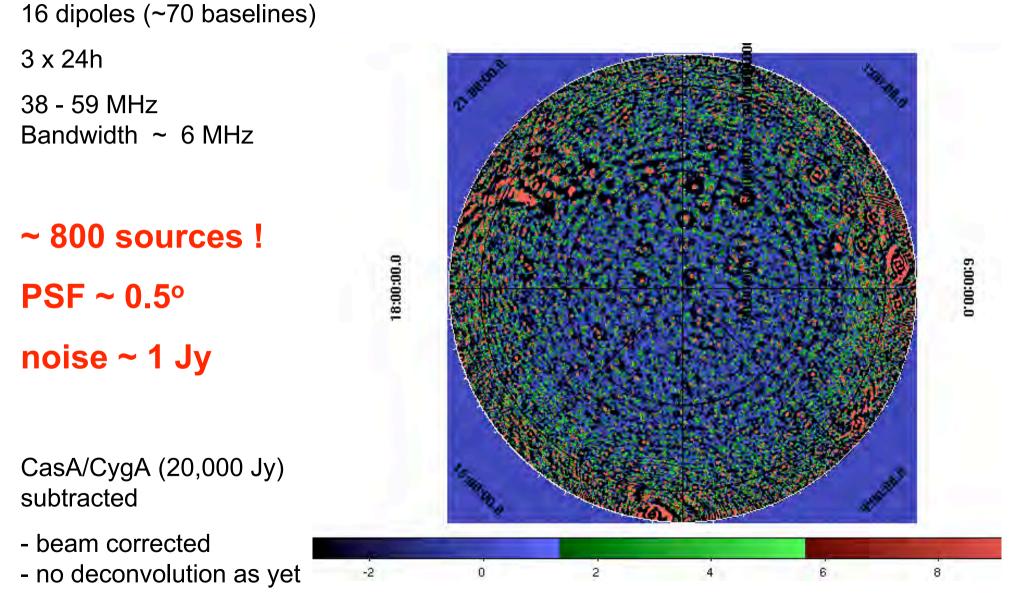
Centered on CasA

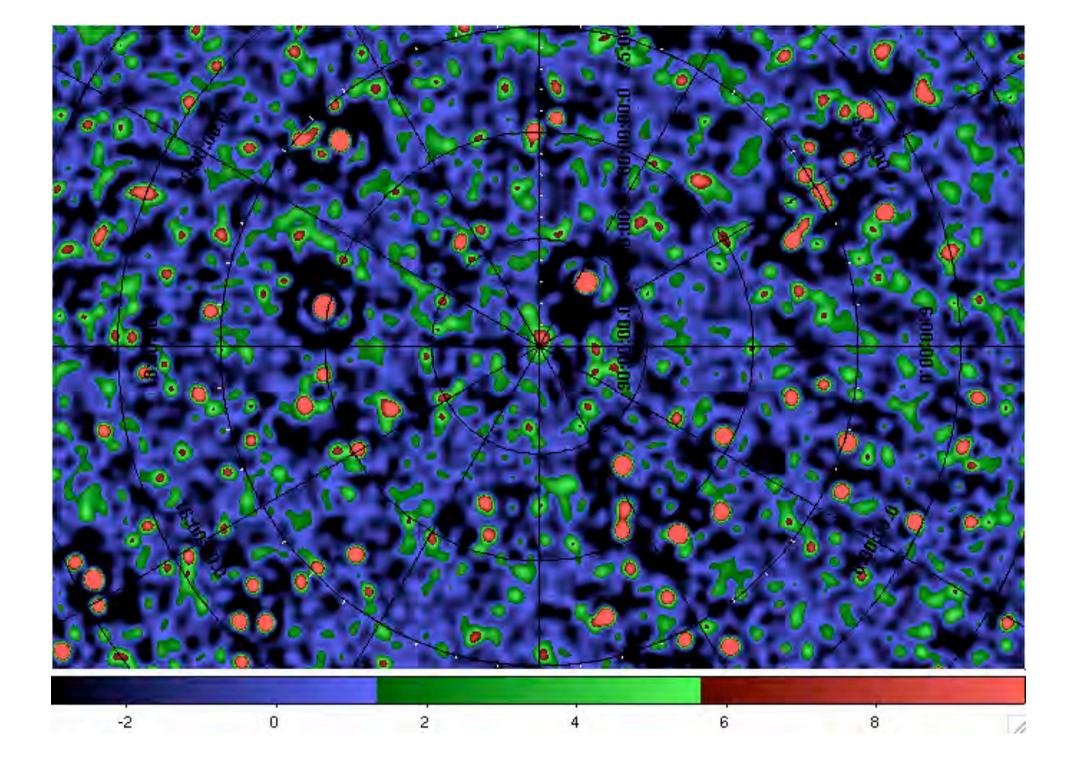
- 24 Feb 2007 (29h obs)
- 0.5 MHz bandwidth
- 16 microstations (15 dipoles and 1 with \sum 48 dipoles)
- only baselines > 5 $\lambda\lambda$
- PSF ~ 0.5°
- ~ 40 sources visible
- CasA: 20,000 Jy (subtracted)
- Image noise ~ 3 5 Jy
 --> peak/noise range ~ 5,000:1
- Thermal noise ~ 0.5 Jy



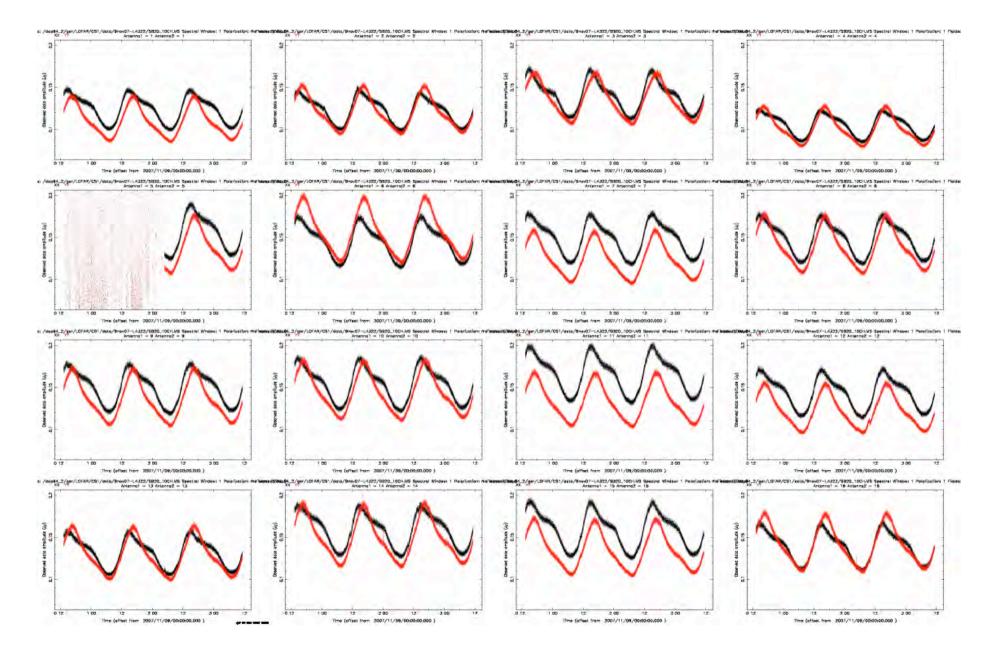
Sarod Yatawatta

Confusion limited LOFAR CS-1 image at ~ 50 MHz (Sarod Yatawatta, Sep07)

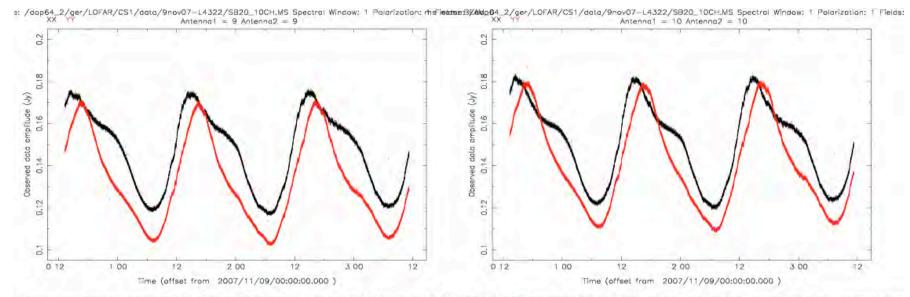


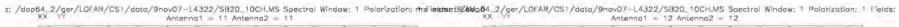


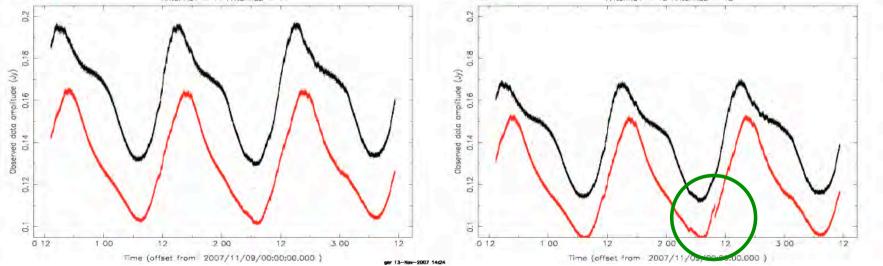
70h HBA (dipoles) observation, 155 MHz, SB20 (9-12 Nov 2007, L4322)



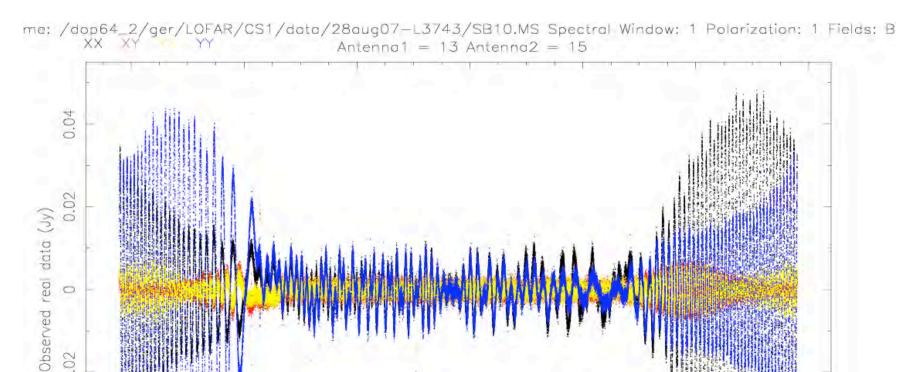
CS008

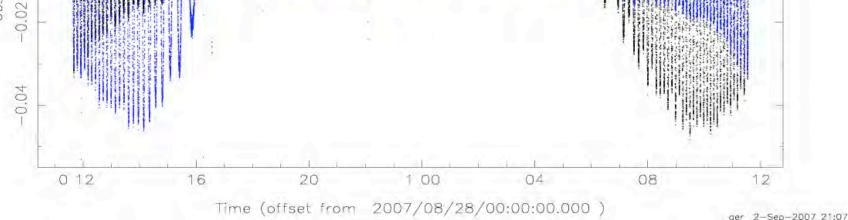






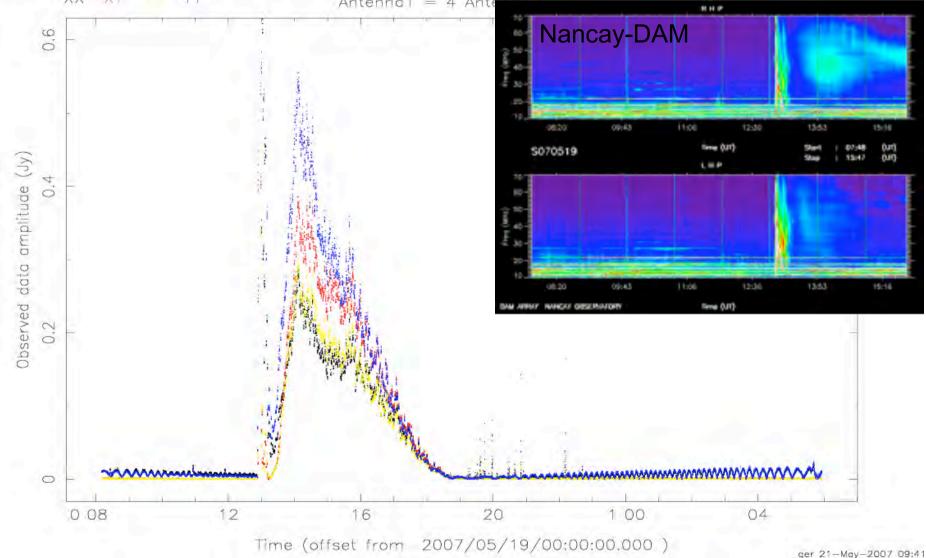
The difference between night and day HBA 220 MHz



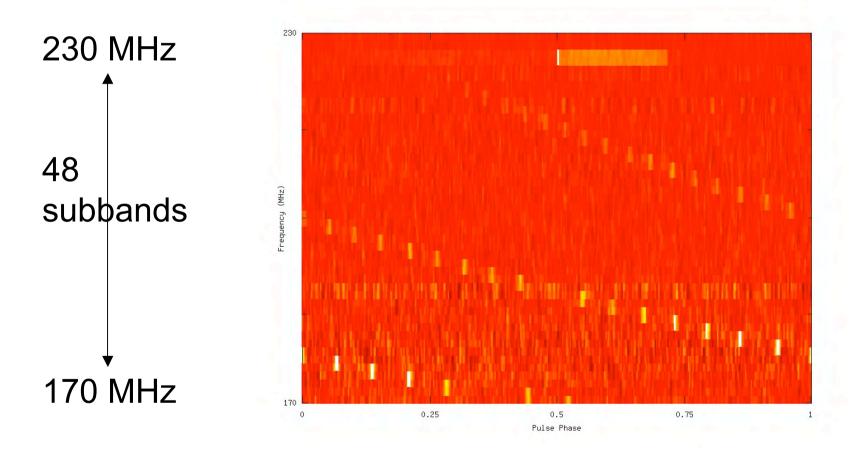


The disturbed Sun ~50 MHz 19May07

p64_4/ger/LOFAR/CS1/data/19may07-L2339/L2007_02339_SB0-5.MS Spectral Window: 6 Polarization: 1 XX XY YY Antenna1 = 4 Antenna2 17

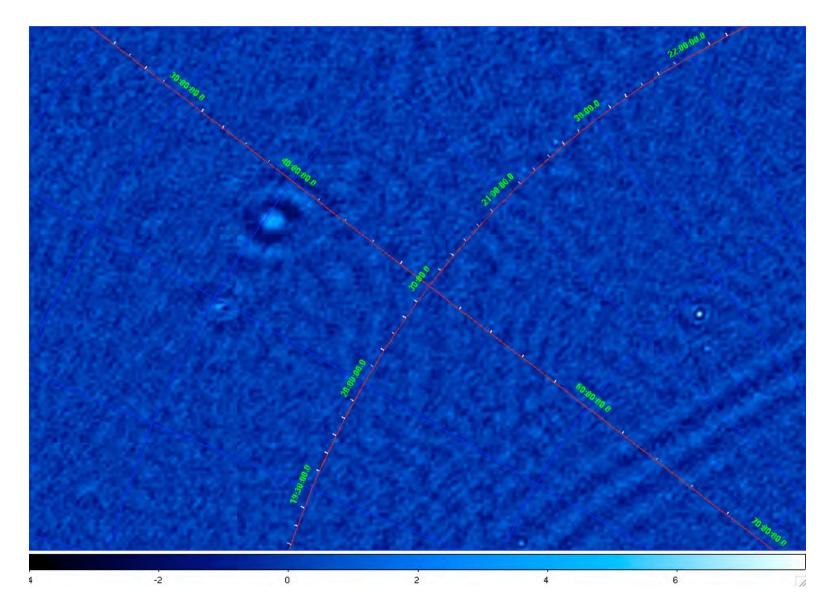


Pulsar B0329+54 dispersion delay (DM = 26.6)

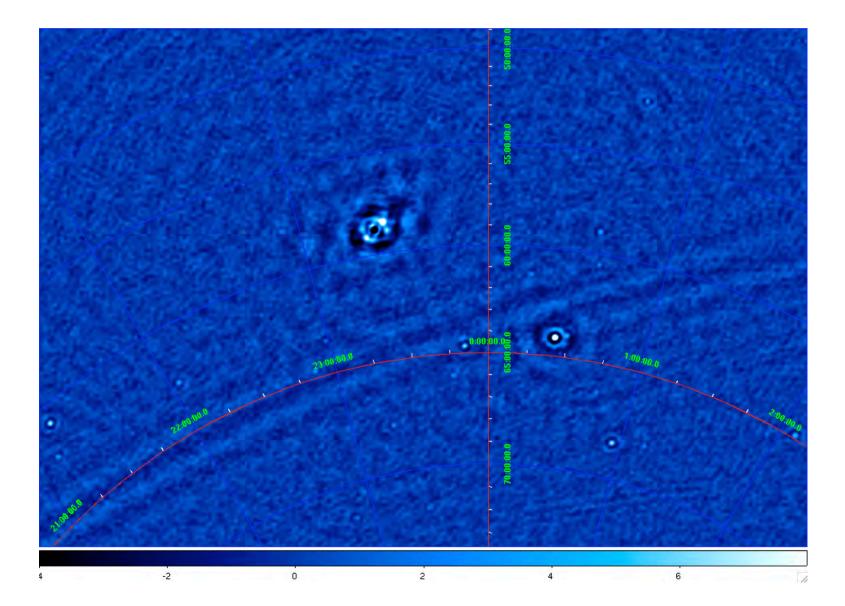


pulse phase (0.71s)

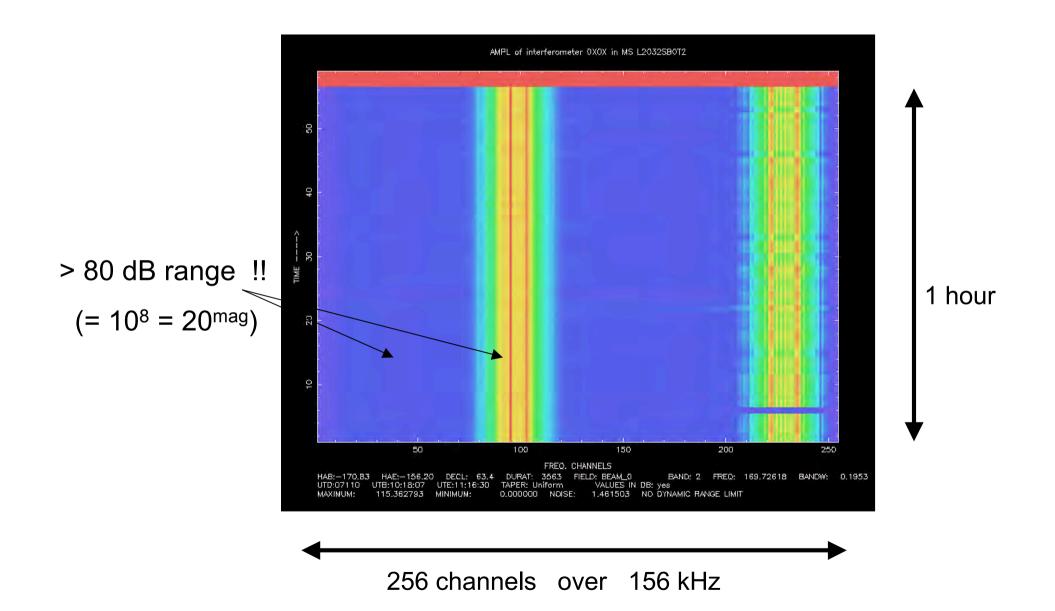
HBA L3743 area near CygA / HB20



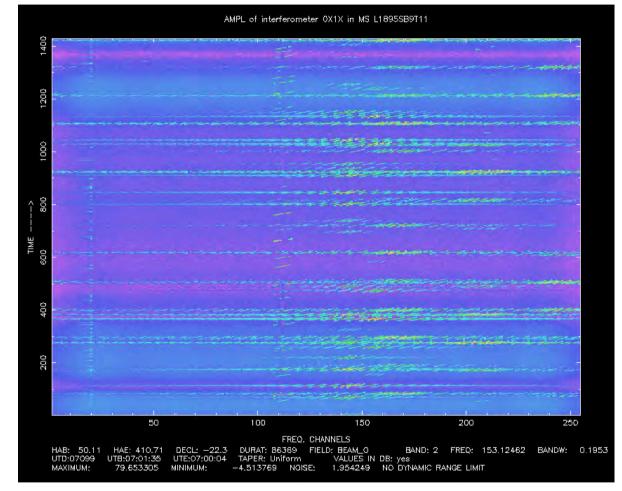
HBA L3743 area near Cas /Tycho



Very intense 'pager signals' at 169.75 MHz and 169.65 MHz



Dynamic spectrum at ~147 MHz 9apr07

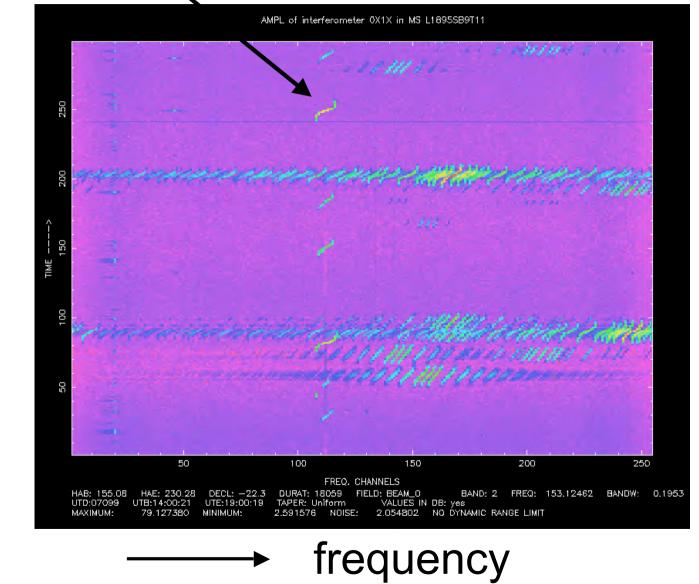


~ 84 dB intensity range !!





LEO satellites around 147 MHz 8 kHz Doppler shift (~ ± 8 km/s)

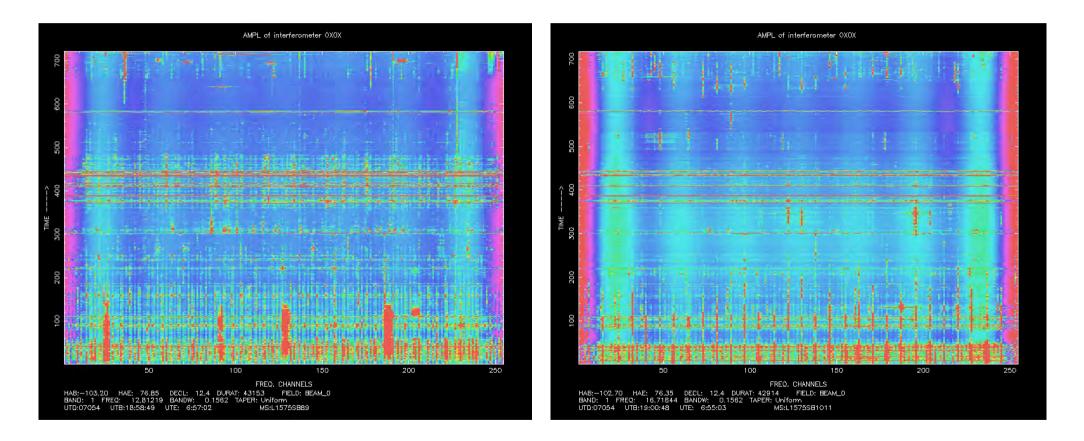


time

RFI in the 10 - 30 MHz LBA band (23 Feb 2007, 12h observation)

12.8 MHz

16.7 MHz



LOFAR (array) calibration

Basic LOFAR calibration framework

(see e.g. Noordam, 2006, LOFAR-ASTRON-ADD No.15)

'Novel' ingredients (compared to standard selfcal)

- Direction/position dependent corrections
 - Phase (ionosphere) => 'non-isoplanaticity'
 - Gain (beam) => elevation/azimuth dependent sensitivity
 - => image-plane vs uv-plane correction solving/treatment
- All sky calibration, wideband synthesis and imaging
 - Global Sky Model needed (spectral index, structural parameters, polarization)
 - w-term always very important (w-projection, speed issue)
- Full polarization Measurement Equation (Hamaker etal)

(Jones matrix description: B, G, E, I, ... : 2x2 matrices , complex and scalar)

Review of calibration problems/challenges and 'solutions'

Question: How to get to the thermal noise in full FOV?

What are relevant 'noise' contributions?

- Thermal (see Table)
- Sidelobe noise from large # sources: ~ $2 \times S_{min} \times \epsilon_{psf} \times \sqrt{N}$
- Classic confusion noise (~ 0.2 mJy at 30 MHz, L ~ 75 km)
- Ionospheric calibration noise (will vary strongly (>10x) !)
- Dynamic Range related (multiplicative noise ..)
- Other: RFI, cross-talk,...

- 1. (Too) low S/N in LBA band in some (many?) fields
 - A serious problem was made more serious due to RESCOPE
 - use wider bandwidth (fewer 'beams') for S/N improvement
 - calibrate phase-screen on HBA (120 MHz) and transfer to LBA
 - use snapshot-calibration approach (=> adds overhead !)
 - Wait for the best nights ...
- 2. Fields with extreme DR requirements (> 10^5 : 1)
 - Due to deconvolution problems on bright sources
 - Instrumental cross talk, faint RFI, closure errors,...
 - Spatial and temporal filtering , subspace projection (see e.g. 3C196 - NCP 'garbage')

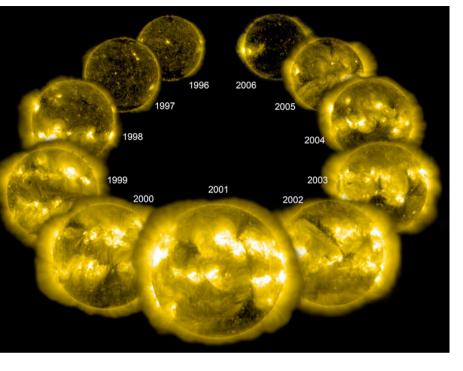
- 3. Too many parameters to solve
 - Can convergence be reached ? Both fundamental and speed issue !
 - Use shorter syntheses to limit station beam-variation
 - More calibration observations and reliance on system stability
 - Use optimized hierarchical calibration schemes
 - Wait for best nights (fewer ionospheric parameters)
- 4. Different station sizes (new issue since rescope)
 - HBA: core NL EU
 LBA: NL EU
 - full FOV calibration/imaging, bandwidth synthesis complications
 - weighting and sensitivity issues
 - not given much thought thusfar

Ionospheric issues

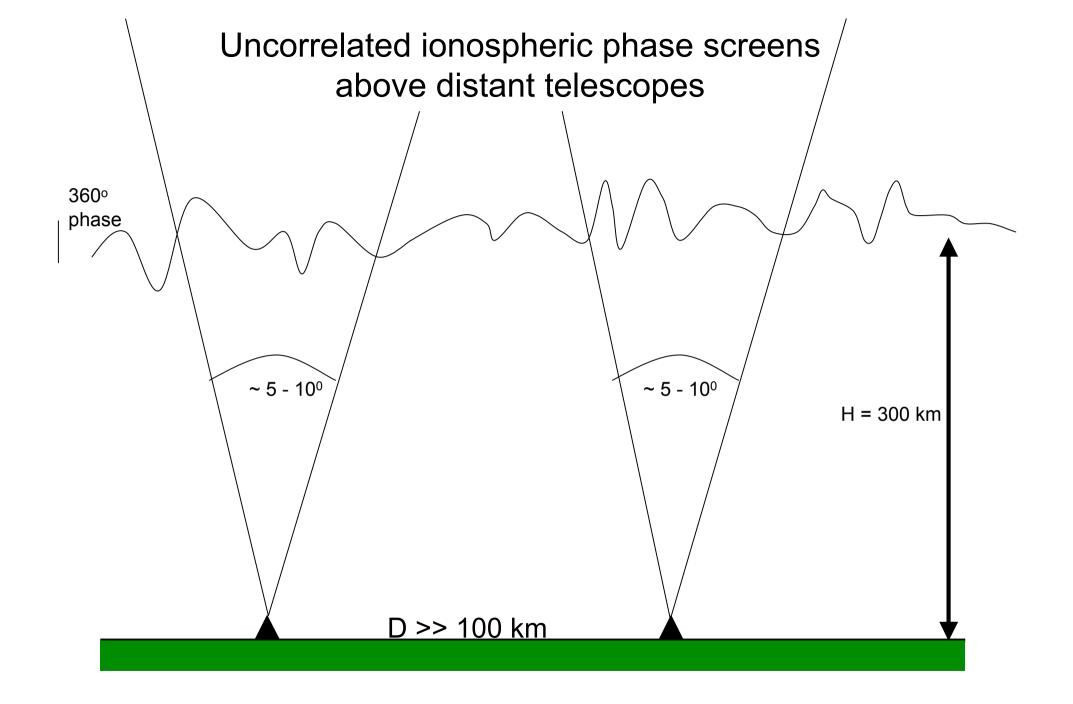
Non-isoplanaticity (low freq, large FOV) Solar cycle (next maximum ~2012) Array scale > refractive/diffractive scale TID's, (Kolmogorov) turbulence

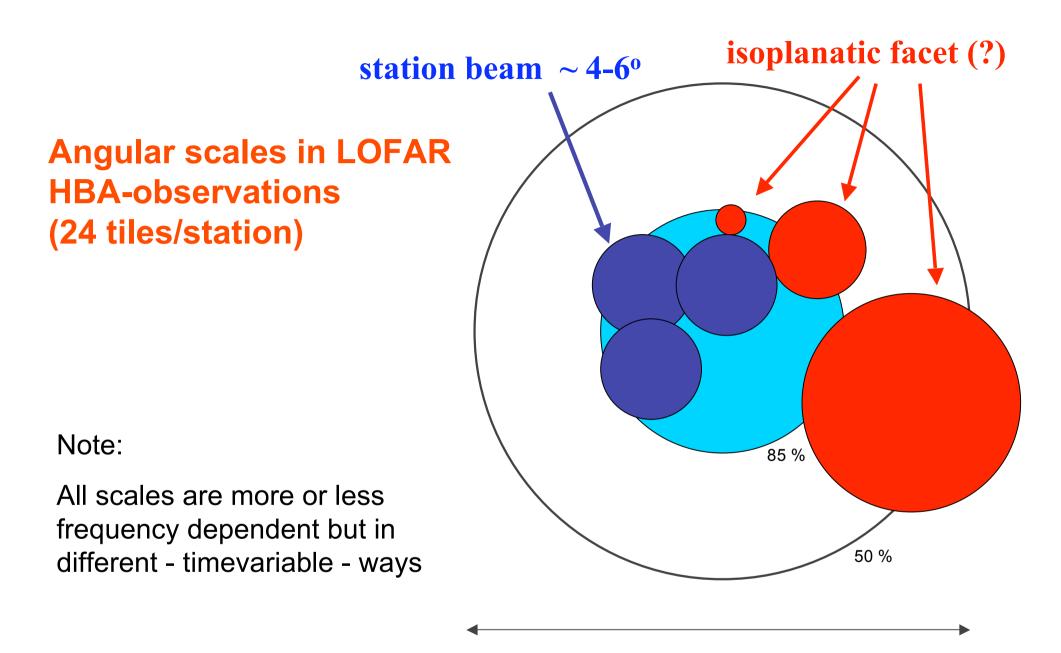
Tools/approaches:

- Bandwidth synthesis (sensitivity, freq-dependence,..)
- Peeling individual sources
- Large scale screen modelling (MIM, Noordam)
- GPS-TEC starting model (Anderson, Mevius)
- Utilize 2-D frozen flow approximation
- Simulations (LIONS, van Bemmel et al)
- 3-D tomography solutions (multiple screens/layers: => EoR KSP needs ?)



Soho-solarcycle, APOD 5 dec07





tile FOV ~ 20 - 25°

WSRT-LFFE preparations and lessons

WSRT

115 - 180 MHz

25m diameter dish

2.7 km baseline

8 x 2.5 MHz x 512 ch

10s integration

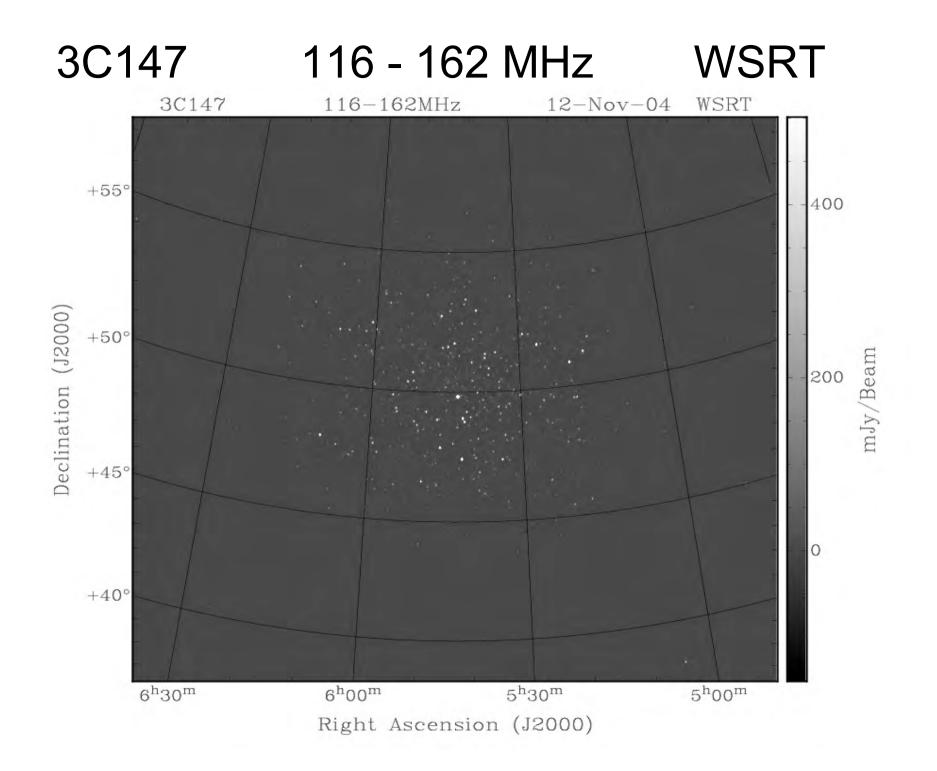
91 baselines

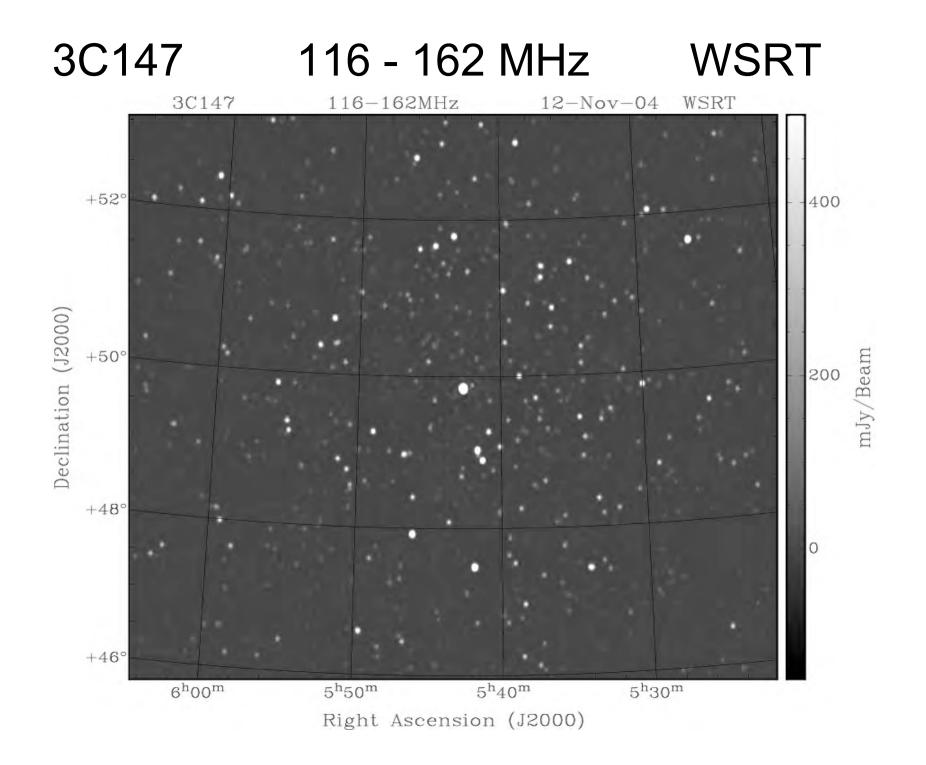
60 GByte dataset/12h

Newstar, AIPS++ and BBS

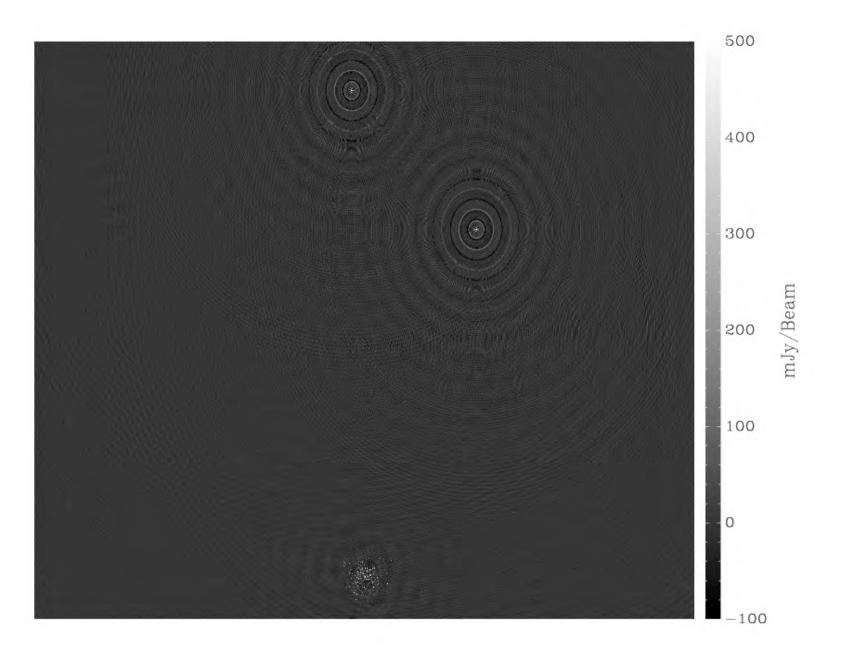
115 - 240 MHz ~35m station (core) ~2 km baselines 20 x 0.2 MHz x 256 ch 10s integration 1128 baselines (N=48) 310 GByte dataset/4h MeqTrees and BBS

LOFAR





3C196 138-157 MHz 20Nov07 WSRT



LOFAR calibration in action (e.g. survey KSP):

Starting visibility data volume (NL array only: HBA, 72 stations, 32 MHz):

- 2500 x 4 x 40,000 x 8 Bytes = 3.2 GByte/s = 25 Gbit/s
- 12h intensive data taking EVERY 24h => 130 TByte/24h

Processing phases overview:

- 1. processing on 1s-1kHz dataset: RFI excision & A-team peel off
- 2. integrate to 5-10 kHz and 5-10s (time-delay smearing limited)
 => 25-100x less data
- 3. Major cycle calibration (~ 3 iterations, e.g. 4%-20%-100% data)
 - global ionospheric refraction (GPS-TEC, MIM)
 - snapshot-calibrator data (external calibration)
 - Interaction with GSM (and LSM)
 - Solving for Cat-I (individually) and Cat-II sources (S/N> 3 per sample)

Dav 1

Day 2-7

4. Cat-I and Cat-II source removal => output cubes (compressed/cleaned (?))

Survey KSP (100 - 100 km baselines) (Leiden-meeting 10-13dec07)

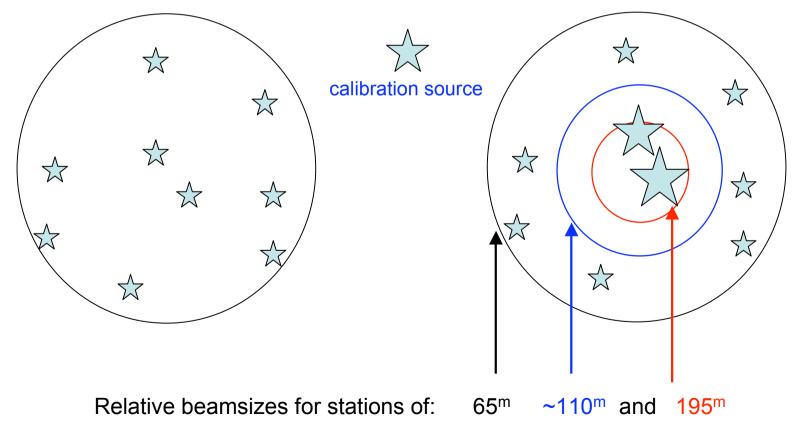
Calibration/processing issues:

- Observation/scheduling strategies and their effects on calibration (e.g. dynamic scheduling ?)
- 2) Involvement during Phase 2 in off-line processing (i.e. days 2-7)
- 3) Update/interaction with Global Sky Model
- 4) Is there a need for storing (calibrated) visibilities and need for possible reprocessing (beyond day 7)
- 5) Polarization calibration: (quasi) real-time vs off-line (==> need visibilities)
- 6) Some other questions:
- IF storage and reprocessing needed: Where / How / Who?
- How many spectral channels in image cubes and why?
- Observing mode priorities: e.g. mozaicing (not ready on day 1...?)

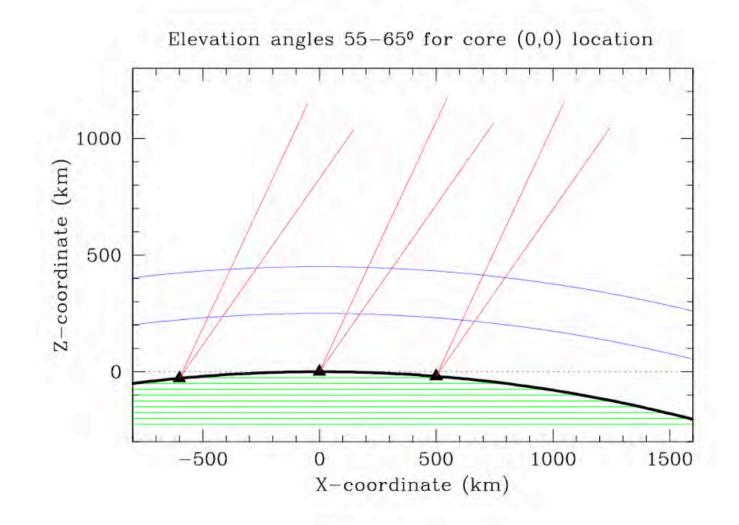
The size of Eu-stations and LOFAR wide-field calibratibility

1) The number of detectable sources per beam does hardly depend on the size (∝ sensitivity) of the station !

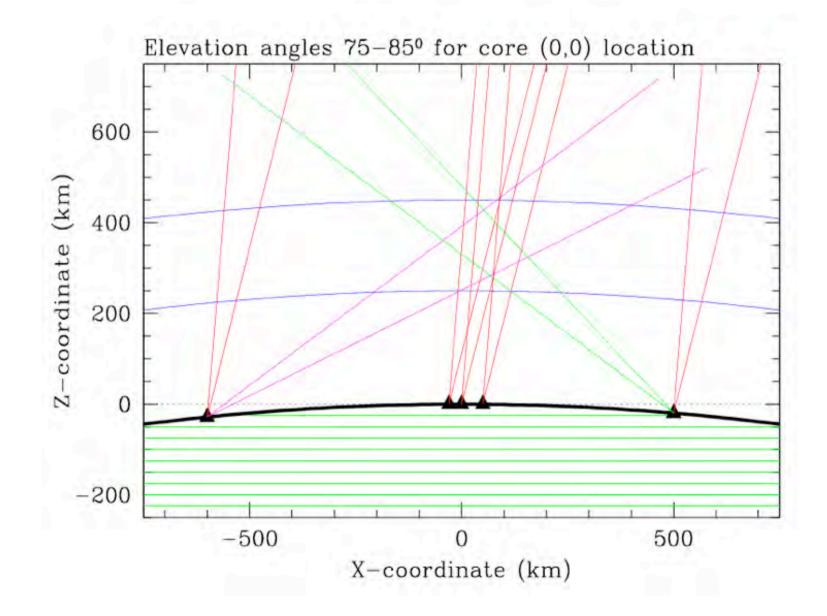
2) But the S/N per source in the smaller effective beam does increase by a factor 3 !!



When stations are > 100 km apart signal from celestial sources do not traverse same ionospheric volume

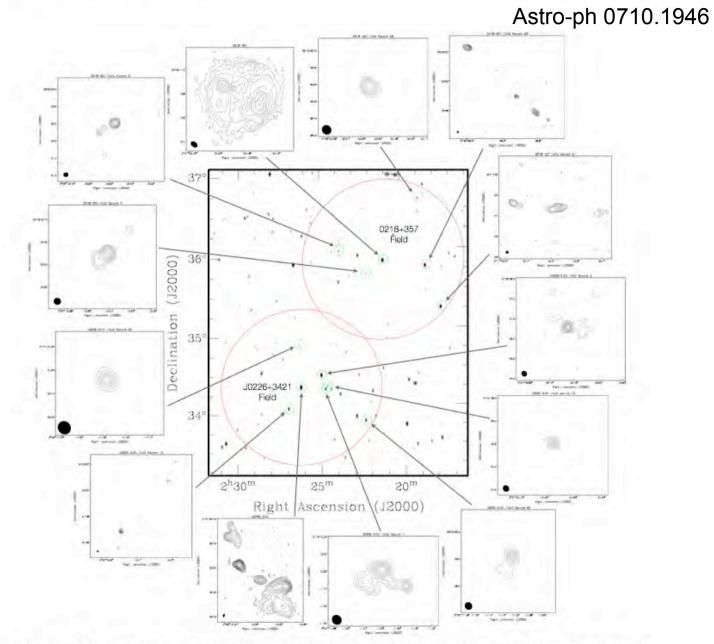


Ionospheric modelling across the wide FOV will require rapid multi beaming and 3-D tomography



Living life on the edge - Wide-field VLBI at 90 cm!

Emil Lenc



Calibrators with structure on <0.25" structure ?!

Global VLBI at 325 MHz

Figure 1: Source detections using wide-field VLBI at 90 cm in 3.1 degree² fields around J0226+3421 and 0218+357.